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# DIVERGENT-FLOW CONTACT-IONIZATION ELECTROSTATIC THRUSTOR FOR SATELLITE ATTITUDE CONTROL AND STATION KEEPING

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#### SUMMARY

A divergent-flow contact-ionization electrostatic thrustor is described herein. This thrustor performed well at thrust levels between 0.89 and 1.56 millinewtons, a range that is applicable to satellite attitude-control and station-keeping missions. Power efficiencies up to 45 percent (excluding vaporizer and neutralizer powers) were obtained for operation at specific impulses from 5000 to 8000 seconds. No damage due to primary ion impingement was detected in about 200 hours of running. Accelerator drain currents were typically less than 2 percent of the beam current. Computer studies indicated an accelerator electrode lifetime in excess of 20 000 hours.

Experimental data verified the computer predictions for electrostatic beam deflection up to about 15<sup>o</sup>. This deflection produced a component of thrust normal to the center plane of up to 30 percent of the total thrust of an undeflected beam.

#### INTRODUCTION

Contact-ionization thrustors using cylindrical electrode geometries are investigated analytically in reference 1. Most experimental effort to date has been directed toward converging flow and plane parallel flow. This report presents theoretical and experimental evaluation of a thrustor based on diverging flow between coaxial cylinders

<sup>\*</sup>Part of the material, ''Experimental Performance of a Low-Thrust, Divergent-Flow, Contact-Ionization Electrostatic Thrustor'' by John F. Staggs and Walter C. Lathem, was presented at the AIAA Second Propulsion Joint Specialist Conference, Colorado Springs, Colo., June 13-17, 1966, and was published in the Journal of Space-craft and Rockets, vol. 4, no. 5, May 1967, pp. 610-615.

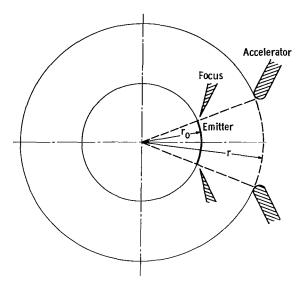


Figure 1. - Coaxial cylinder configuration.

(refs. 1 and 2), as shown in figure 1. The thrustor develops a thrust within a range suitable for attitude control and station keeping of satellites in the 200- to 700-kilogram mass range (ref. 3). With electrostatic beam deflection, a thrustor can perform both attitude-control and station-keeping functions without thrustor gimbaling.

Two important thrustor performance requirements are long operational life and high efficiency. For satellite missions of several years duration, long life is more important, since these thrustors will require only a small portion of the satellite power supply.

To obtain long operational life, several components must be considered. The life-times of certain components, such as the porous tungsten ionizer and the ionizer heater element, are dependent to a large degree on the state of the art. Accelerator grid life, however, is strongly dependent on the optical design of the thrustor; that is, the optics will determine the rate of accelerator erosion due to charge-exchange ion impingement. The primary advantage of a diverging ion beam is that both the ion density and the neutral atom density are reduced in the accelerator aperture area, and the charge exchange ion formation rate is thus reduced. (The charge-exchange interaction rate is directly proportional to each of these quantities.)

In this report, the design, fabrication, and testing of a divergent-flow contactionization thrustor is described in detail.

#### THEORETICAL CONSIDERATIONS

### **Electrode Geometry**

The electrode system used in the experimental thrustor was designed by using an

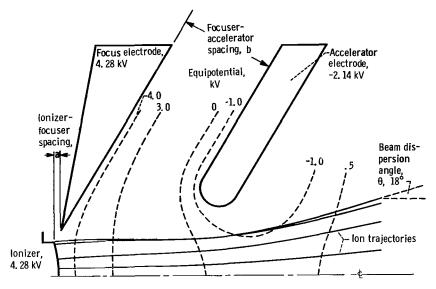


Figure 2. - Cross section of ionizer, electrodes, and optical characteristics from digital computer program.

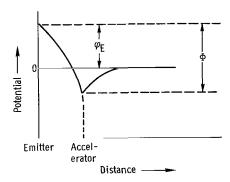


Figure 3. - Ideal potential distribution.

electrolytic tank analog (ref. 4) and a digital computer program (ref. 5). The goal was to provide a reasonably high current density with no primary ion impingement on the accelerator. A secondary goal was simplicity of electrode fabrication and alinement. A cross-sectional sketch of the electrode shapes arrived at is shown in figure 2. Also shown are typical ion trajectories and equipotential lines for the Poisson solution obtained with the digital program. The ideal potential distribution is shown in figure 3.

The computed variation of current density with total voltage can be compared with basic theory by considering the theoretical equation for space-charge limited flow between coaxial cylinders given in reference 2 as

$$j_{E} = \frac{4\epsilon_{o} \left(\frac{2q}{m}\right)^{1/2} \Phi^{3/2}}{9r_{o}r\beta^{2}}$$

(All symbols are defined in appendix A.) When cesium is used, this equation becomes (in SI units)

$$j_E = 4.74 \times 10^{-9} \left( \frac{\Phi^{3/2}}{r_0 r \beta^2} \right), \quad A/sq m$$

In the experimental configuration  $r_0 = 3.0$  millimeters and r = 6.0 millimeters ( $\beta = 0.279$ ). The solution of the preceding equation using these values yields the upper curve of figure 4. Digital solutions for the final electrode configuration are also shown for two values of the focuser-accelerator spacing b. The ionizer-focuser spacing a was held constant at 0.127 millimeter, and the accelerator aperture was maintained at 3.0 millimeters. The computed current density for the thrustor configuration is lower than the ideal theoretical values for two reasons. First, the overall electric field is reduced by the aperture effect. Second, the presence of a focusing electrode acts to reduce the electric field at the ionizer. This latter effect is apparent from inspection of figure 5 which shows the results of varying the spacing a, from 0.0 to 0.191 millimeter

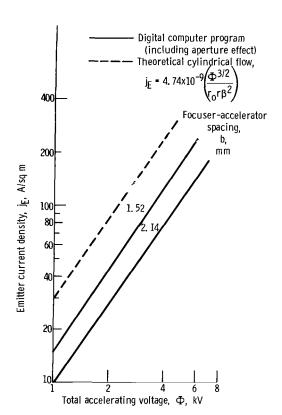


Figure 4. - Comparison of theoretical and digital computer program current densities as functions of total accelerating voltage for two values of accelerator focuser spacing.

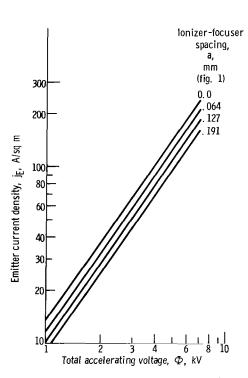


Figure 5. - Effect of ionizer-focuser spacing on emitter current density from computer program. Focuser-accelerator spacing, 2.14 millimeters.

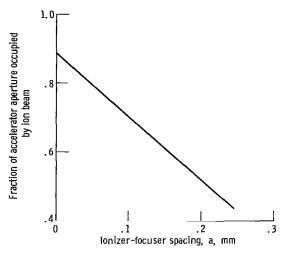


Figure 6. - Fraction of accelerator aperture occupied by ion beam as function of ionizer-focuser spacing.

while holding b constant.

The fraction of accelerator aperture occupied by the beam as a function of the ionizer-focuser spacing a is shown in figure 6. Figure 6 shows that beam divergence is a sensitive function of this spacing.

#### Accelerator Electrode Life

The useful life of an ion thrustor accelerator electrode is limited by the sputtering rate of the electrode material due to impinging ions. The impinging ions can be of two types, primary beam ions not properly focused or ions formed in the electrode aperture area by charge exchange of primary ions and neutrals from the emitter.

Figure 2 (p. 3) shows that, theoretically, the divergent flow thrustor beam occupies only about 60 percent of the accelerator aperture. This precludes the possibility of erosion due to primary ions. There will, however, be erosion from charge-exchange ions. As stated earlier, one of the theoretical advantages of the divergent-flow concept is the reduced ion and neutral density in the aperture area, which should result in a reduction in the rate of charge-exchange erosion, thereby extending thruster lifetime. In order to predict the accelerator charge-exchange erosion and thrustor lifetime, an analysis was made utilizing both the electrolytic tank analog and the computer programs. This analysis yielded the calculated erosion patterns shown in figure 7. The parameters used for the study are given in figure 7, which is drawn for 20 000 hours of operation at these conditions. For details of the calculation and further discussion of the techniques used in this study, see appendix B and also references 4 and 6.

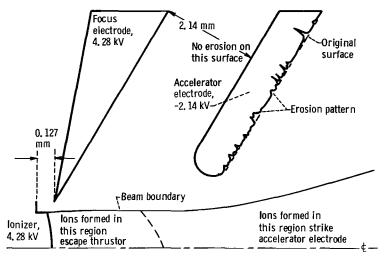


Figure 7. - Theoretical accelerator erosion pattern due to charge-exchange ion impingement after 20 000 hours at 163 amperes per square meter. Total beam current, 16.3 milliamperes; neutral atom loss, 1.0 percent of total beam current.

#### EXPERIMENTAL APPARATUS

#### Thrustor Design

A cross-sectional sketch of the experimental thrustor configuration is shown in figure 8 and photographs are shown in figure 9. The overall size of the thrustor (including a grounded shielding screen not shown in the photographs) is 2.5 by 7.5 by 14.0 centimeters. The total weight of the thrustor, excluding the vaporizer, is approximately 0.15 kilogram.

The accelerator electrode was made of copper, so that back-sputtered material

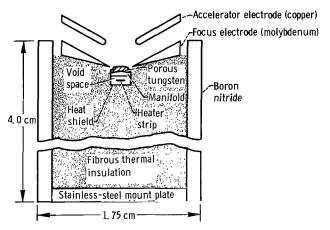
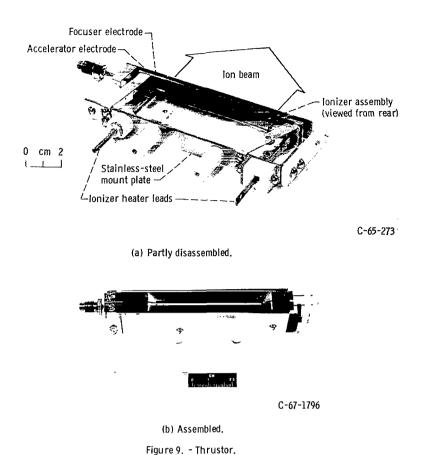


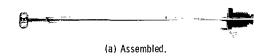
Figure 8. - Cross section of thrustor showing overall dimensions of supporting structure and materials used.



would not clog the porous ionizer. It was also made in two halves to allow electrostatic

beam deflection by varying the potential on each half. The ionizer, electrodes, and heater lead-in rods were all mounted from the stainless-steel mount plate (fig. 9(a)), which was maintained ationizer and focuser electrode potential. The focuser was made of molybdenum. Boron nitride sideplates confined the fibrous thermal insulation material. In operation, a stainless-steel grounded screen surrounded the thrustor to prevent stray electrons from reaching the thrustor.

The ionizer assembly is shown in figure 10. The ionizer manifold consists of a Ushaped channel of 0.127-millimeter-thick tungsten sheet electron-beam-welded to the porous tungsten ionizer. End plates, feed tube, and support tabs are of tantalum. Another U-shaped channel of tungsten is welded to the back of the manifold to form an enclosure for the heater strip (fig. 8). Heating the ionizer is accomplished by radiation from the strip. The ionizer assembly, which is approximately square in cross section (with each side 2.2 mm long), has an ion emitting surface area of 1.0 square centimeter. This convex emitting surface has a radius of 3.0 millimeters, a chord length of 1.52 millimeters, and an overall length of 6.35 centimeters.



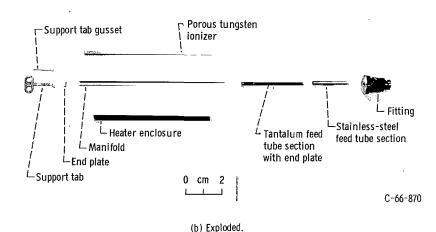


Figure 10. - Ionizer assembly.

#### **Test Facility**

A schematic drawing of the test setup is shown in figure 11. The main chamber of the vacuum facility is 4.5 meters long by 1.5 meters in diameter and contains a liquid-nitrogen-cooled condenser. The facility was typically pumped to a pressure of from  $10^{-6}$  to  $10^{-8}$  torr (approx.  $10^{-4}$  to  $10^{-6}$  N/sq m) during tests by using three 0.9-meter oil diffusion pumps. Actual pressure depended on operating conditions. A 0.9-meter-diameter gate valve separated the main chamber from the thrustor chamber, which was approximately 1 meter long by 1 meter in diameter. A more detailed description of the vacuum facility is given in reference 7. All thrustor electrical connections were made through ceramic insulators at the rear of the thrustor chamber.

An isolation screen in the exit plane of the thrustor was maintained at electrical ground to prevent electrons from reaching the electrical leads in the thrustor chamber.

#### Instrumentation

The meters used in measuring beam currents and accelerator drain currents had an accuracy of  $\pm 1.0$  percent of full scale. They were provided with multiple shunt circuits

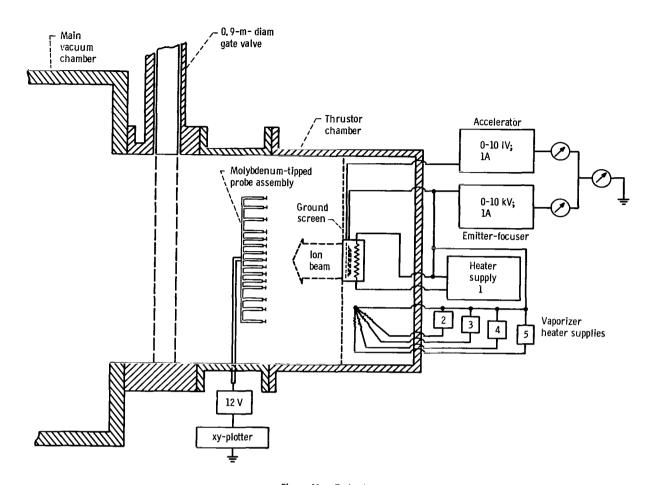


Figure 11. - Test setup.

to allow full-scale current readings from 0.1 to 30 milliamperes.

A molybdenum-tipped probe assembly was used to investigate beam dispersion, to obtain a check of the total ion beam current obtained from the meter readings, and to check the amount of beam vectoring when a differential voltage was applied to the two accelerator halves. The assembly of 15 buttons, each 12.7 millimeters in diameter, was located 35.6 centimeters downstream of the thrustor. As the assembly traversed the ion beam, the currents produced by ions striking the probe buttons created a voltage drop across 100-ohm terminating resistors. A system capable of handling 20 data points per second was used to sample the 15 buttons plus a position indicator signal in rotation. In this way, each button was sampled approximately 75 times per minute. The probe traveled about 40 centimeters per minute to give approximately two data points per centimeter of travel for each button. A more detailed discussion of molybdenum-tipped probe operation is given in reference 8.

#### RESULTS AND DISCUSSION

#### Ionizer Current Density and Critical Temperature

During testing of the thrustor, the ionizer-to-focuser spacing was held at 0.127 millimeter, and two values of focuser-to-accelerator spacing were used. A comparison of the experimental current densities with computer predicted values at various cesium flow rates is given in figure 12 for b=1.52 and 2.14 millimeters. The maximum current density obtained experimentally was 160 amperes per square meter at a field strength of  $3.0\times10^6$  volts per meter. As predicted by the computer program, varying  $\Phi/\Phi_{\rm E}$  from 1.5 to 3.0 with constant  $\Phi$  did not significantly change the experimental current density.

A high-quality porous tungsten designated "E-4" in reference 9 was used throughout the program. The samples were fabricated from 1- to 5-micron-diameter spherical powder and were about 79 percent of theoretical density. Critical temperatures for various ionizer current densities were obtained from pellet samples and are reported in reference 10. These values are compared with results of this program in figure 13. Also included in the figure is the zero-field Taylor-Langmuir curve for solid tungsten taken from reference 11. In the pellet evaluations of reference 10, the critical temperature

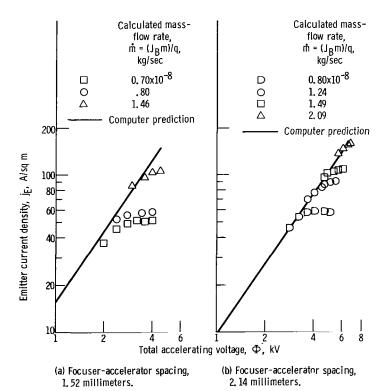


Figure 12. - Comparison of experimental current densities with computer predicted values. Ionizer-focuser spacing, 0.127 millimeter.

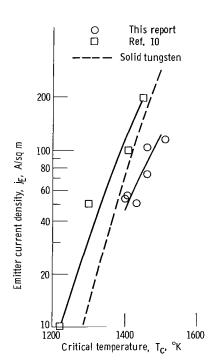


Figure 13. - Comparison of critical temperature measurements with those of reference 10 and with the zero-field Taylor-Langmuir curve for solid tungsten (ref. 11).

points were taken as points of minimum neutral fraction, whereas the data reported herein reflect temperatures at which the current density was 95 percent of its maximum value. At these temperatures, the accelerator drain currents were near a minimum. Also, since the ionizer temperature was somewhat nonuniform along its length, the critical temperature was taken to be the coolest point on the ionizer surface.

#### **Accelerator Drain Currents**

Typical data of the ratio of total accelerator drain current  $J_A$  to beam current  $J_B$  as a function of total accelerating voltage  $\Phi$  are presented in figures 14 and 15. In figure 14, data are compared for three different flow rates. A possible explanation of the reversal of the slope of the curves as the voltage is increased might be field enhancement of thermionic emission from the cesium-coated accelerator (ref. 12). In figure 15, results obtained with a background pressure of  $7.0\times10^{-7}$  torr (approx.  $9\times10^{-5}$  N/sq m) are compared with those obtained at the same mass-flow rate but with a background pressure of  $6.0\times10^{-5}$  torr (approx.  $8\times10^{-3}$  N/sq m) of oxygen. When oxygen is admitted to the system, it may change the thermionic emission characteristics of the cesiated copper accelerator surface as well as have a decarburizing or oxidizing effect on the ionizer (ref. 13). In every instance the addition of oxygen reduced the accelerator drain currents. The exact mechanism of the change is not fully understood, but it is believed

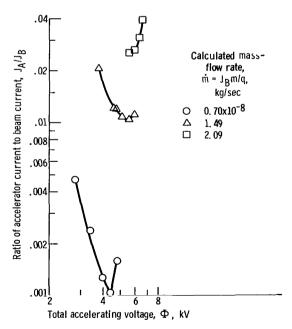


Figure 14. - Ratio of accelerator drain current to beam current as function of total accelerating voltage for several mass-flow rates. Background pressure, 8x10<sup>-7</sup> torr (approx. 10<sup>-4</sup> N/sq m).

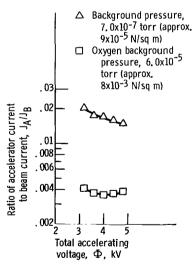


Figure 15. - Effect of oxygen atmosphere on accelerator drain currents. Calculated mass-flow rate, 8. 9x10<sup>-9</sup> kilogram per second.

that the reduction in drain currents occurs too rapidly after the addition of oxygen (on the order of 1 min) to be caused by decarburization of the ionizer and is probably due to a combination of the other effects.

Possible sources for accelerator drain currents include direct impingement, charge-exchange ion impingement, leakage currents across cesium-coated insulators, thermionic electron emission from a hot cesium-coated accelerator, and secondary emission resulting from ion impingement.

The digital computer program predicted no direct ion impingement. After a total of 200 hours of thrustor operation at an average beam current of 6.2 milliamperes, the accelerator grid showed no observable erosion in the areas which might be struck by ions from the ionizer.

Some charge exchange, however, is inevitable. The magnitude depends not only on the neutral fraction but also to a large extent on the optics of the system. A diverging system reduces the ion density and the neutral atom density in the accelerator aperture region and thus minimizes the rate of charge-exchange interactions. From the charge-exchange study mentioned previously, the total charge-exchange impingement rate was calculated to be about  $10^{12}$  ions per second, or approximately 0.001 percent of a 16.0-milliampere ionizer current. Charge-exchange, then, is probably a negligible contributor to the drain currents observed.

Since ion impingement (both direct and from charge exchange) appears to be negligible, secondary electron emission would also be very small. All insulators were to the rear of the thrustor and were therefore not subject to cesium coating. Leakage currents across these insulators were negligible. Based on these arguments, it is likely that nearly all the experimental drain currents can be attributed to thermionic electron emission from the upstream face of the accelerator, which probably became coated with cesium atoms from the ionizer.

Two important factors affecting the neutral fraction besides the characteristics of the tungsten are (1) temperature uniformity over the ionizer and (2) matching the arrival rate profile of cesium of the emitting surface with the ion extraction rate profile from

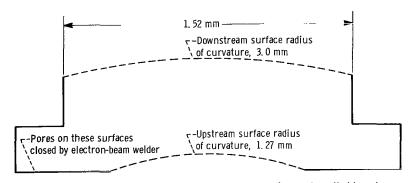


Figure 16. - Cross section of porous tungsten ionizer showing surfaces that have been closed with electron-beam welder.

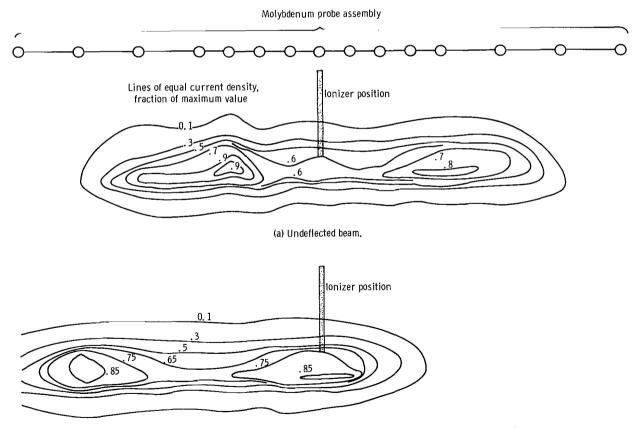
that surface.

The first factor can be handled by designing the ionizer and heater to assure temperature uniformity and/or operation with the coolest portion of the ionizer above the critical temperature.

The second factor is taken care of by contouring the back (upstream face) of the porous tungsten. The final shape (fig. 16) was obtained by setting up an analog of the flow through the porous tungsten by using the electrolytic tank. In this figure, the dashed lines show the contour of the porous surfaces and the solid lines represent surfaces where the pores have been "washed" closed with an electron-beam welder (short duration heating, so that a thin surface layer is melted).

#### Optical Characteristics and Thrust Vectoring

Optical characteristics of the thrustor were investigated by beam probe measurements. Figure 17 shows contour plots of the current-density variation through a cross

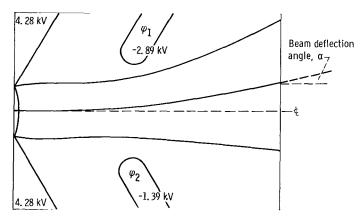


(b) Deflection voltage of 1.5 kilovolts applied to split accelerator. Beam deflected about 15°.

Figure 17. - Current contour map from molybdenum button probe measurements showing lines of equal current density. Total current calculated from this figure, 14.7 milliamperes.

section of the beam 35.6 centimeters downstream of the ionizer. Figure 17(a) shows an undeflected beam, while figure 17(b) shows the effect of a 1.5-kilovolt deflection voltage. This deflection voltage was obtained by increasing the voltage on one accelerator half by 750 volts and decreasing the voltage by the same amount on the other half.

While these data were being taken, the metered beam current was 9.4 milliamperes. A rough integration of this contour map yielded a current of about 14.7 milliamperes. The difference is due both to secondary emission from the probes and to inaccuracies in drawing the map. Although these current values do not show good agreement, the qualitative profile and magnitude of beam deflection obtained agreed with theoretical predictions. For example, it was determined from the contour map that 90 percent of the beam lies within a dispersion angle  $\theta$  of about 15°. This value agrees well with the 18° angle predicted by the digital computer solution (fig. 2, p. 3). The double peaked profile of the beam had also been predicted from the computer results.



(a) Differential voltage,  $\Delta \varphi$ , 1.5 kilovolts.

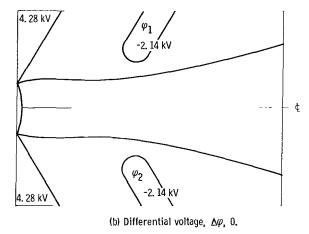


Figure 18. - Effects of applying differential voltage  $\Delta \varphi$  to two halves of split accelerator. Solutions obtained from digital computer;  $\Delta \varphi = \varphi_1 - \varphi_2$ .

The beam deflection angle  $\alpha$  was analyzed theoretically, and typical results are shown in figure 18 for a differential voltage  $\Delta \varphi$  of 1.5 and 0 kilovolt. The deflection angle  $\alpha$  (fig. 19) is approximately 1.0 for every 100 volts of deflection voltage. (This angle is not to be confused with the dispersion angle  $\theta$ , which is a measure of the normal spread of the beam.) Experimental results for beam deflection are compared with theory in figure 20. The deflection angles determined from the probe contour maps are shown as data points and are in good agreement with theory.

The calculated thrust component normal to the center plane  $T_y$  as a fraction of  $T_x$  for  $\alpha=0$  is plotted against the calculated deflection angle in figure 21 (as in fig. 19,  $T_x=T_{res}$  for  $\alpha=0$ ). With a deflection of 15°,  $T_y$  is about 30 percent of  $(T_x)_{\alpha=0}$ .

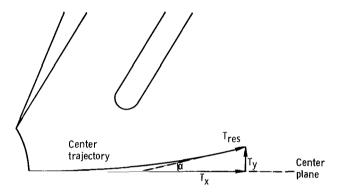


Figure 19. - Cross section of thrustor showing deflection angle  $\,\alpha\,$  and thrust vectors,

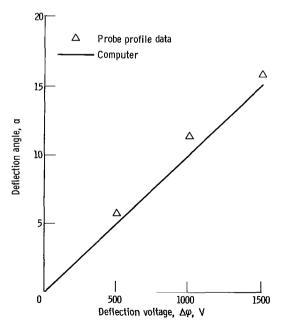


Figure 20. - Beam deflection angle as function of deflection voltage.

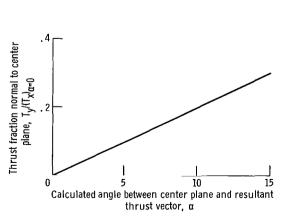


Figure 21. - Thrust component normal to center plane (as fraction of undeflected total thrust) as function of deflection angle.

#### **Overall Performance**

The thrustor yielded overall performance which approximates the requirements for certain satellite attitude-control and station-keeping missions in which a thrust range of 0.445 to 1.78 millinewtons (0.1 to 0.4 mlb) is needed (ref. 3). Stationary-satellite missions require control systems that are lightweight, efficient, and long lived. In the continuous corrections mode of operation, approximately 0.445 millinewton (0.1 mlb) of thrust is needed for every 160 kilograms of satellite weight (ref. 3). Figure 22 shows the calculated thrust as a function of beam current for three different specific impulses (thrust calculated from measured beam currents and net accelerating voltages). This variation in specific impulse was achieved by changing  $\Phi/\varphi_{\rm E}$  while maintaining constant  $\Phi$ .

Figure 23 shows power efficiencies as a function of specific impulse, calculated from

$$\eta_{\mathbf{P}} = \frac{\mathbf{P}_{\mathbf{B}}}{\mathbf{P}_{\mathbf{B}} + \mathbf{P}_{\mathbf{h}} + \mathbf{P}_{\mathbf{A}}}$$

These efficiency values do not include vaporizer or neutralizer powers because these components were not optimized for the tests. Accelerator drain power losses are included. Data are presented for accelerator-to-focuser spacings of 1.52 and 2.14 millimeters.

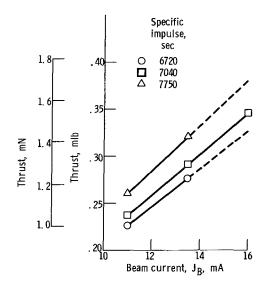


Figure 22, - Calculated thrust as function of experimental beam current for three values of specific impulse,

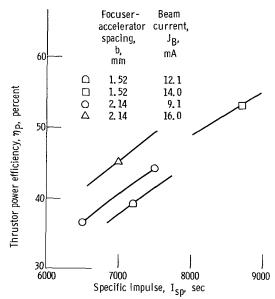


Figure 23, - Thrustor power efficiency as function of specific impulse.

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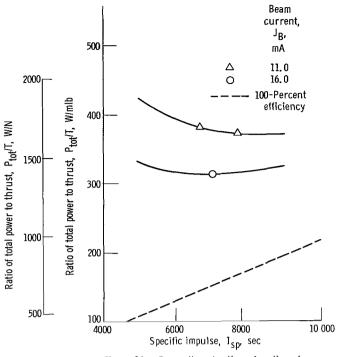


Figure 24. - Power-thrust ratio as function of specific impulse.

Figure 24 shows the variation of power-thrust ratios with specific impulse at different beam current levels. The dashed curve represents a 100-percent-efficient thrustor.

Figures 23 and 24 show that efficiency could be improved considerably. However, as previously noted, the more important factor for satellite applications is lifetime. Thus far, over 200 hours of testing have indicated no problems with accelerator erosion. More testing would be required to verify the accelerator erosion predictions fully. Optimization of components such as the ionizer heater assembly, electrode support structures, and thermal insulation package should improve overall performance.

#### CONCLUDING REMARKS

A contact-ionization electrostatic thrustor was designed, fabricated, and tested. Thrust levels between 0.89 and 1.56 millinewtons (0.2 and 0.35 mlb) were produced at power efficiencies up to 45 percent in the specific-impulse range from 5000 to 8000 seconds. The optical characteristics were such that primary ion impingement on the accelerator electrode was negligable or nonexistent, and drain currents were about 2 percent or less of the beam current. Computer studies and numerical analysis predicted elec-

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trode lifetimes in excess of 20 000 hours.

Electrostatic ion beam deflection worked well for producing a thrust component normal to the center plane. By deflecting the ion beam 15°, a thrust is produced in a direction perpendicular to the thrustor center plane which is about 30 percent of the original total thrust. With this technique, both attitude-control and station-keeping functions could be performed with the same thrustor, and the need for mechanical gimbaling would thus be eliminated.

Lewis Research Center,
National Aeronautics and Space Administration,
Cleveland, Ohio, August 16, 1967,
120-26-02-06-22.

# APPENDIX A

# **SYMBOLS**

a	ionizer-focuser spacing	w	width of emitter chord
b	focuser-accelerator spacing	X	normal distance from emitter
f	ratio of neutral atom emission		surface to center of charge- exchange volume
	rate to ion emission rate	37	•
$I_{sp}$	from emitter specific impulse	Y	normal distance from plane of symmetry of thrustor to center of charge-exchange
J	current		volume
j	current density	α	beam deflection angle
k	Boltzmann constant	β	function of $r/r_0$ (ref. 2)
m	mass of atom	$\eta_{\mathbf{P}}^{}$	power efficiency
'n	mass-flow rate	$\theta$	beam dispersion angle
Ň	charge-exchange ion formation rate	$\mu$	arrival rate at charge- exchange volume
P	power	ν	emission rate from ionizer
Q	cross section for charge-	ρ	number density
	exchange interaction	Φ	total accelerating voltage
q	charge on electron	arphi	voltage
r	radius of outer cylinder of	Subscripts	:
	coaxial cylinder electrode system	Α	accelerator
$\mathbf{r}_{\mathbf{o}}$	radius of inner cylinder (emit-	В	beam
0	ter) of coaxial cylinder	E	emitter
	electrode system	h	ionizer heater
T	temperature	j	j <sup>th</sup> plane parallel to yz-plane
$\left\{egin{array}{l} \mathbf{T_{res'}} \\ \mathbf{T_{x'}}, \mathbf{T_{y}} \end{array}\right\}$	thrust vectors	k	k <sup>th</sup> plane parallel to xz-plane
		Superscrip	ts:
V	charge-exchange volume	0	neutral atom
$\overline{\mathbf{v}}$	mean velocity	+	positive ion

#### APPENDIX B

#### CHARGE-EXCHANGE EROSION CALCULATIONS

Calculating the effect of charge-exchange ion erosion on an ion thrustor accelerator requires knowledge of

- (1) The rate charge-exchange ions are formed in the primary ion beam region
- (2) The arrival rate of charge-exchange ions as a function of energy and angle of incidence for each element of accelerator electrode area
- (3) The sputtering rate of the accelerator material

The configuration used for this figure is shown in figure 25. It will be helpful to refer to this figure in following the analysis to be presented.

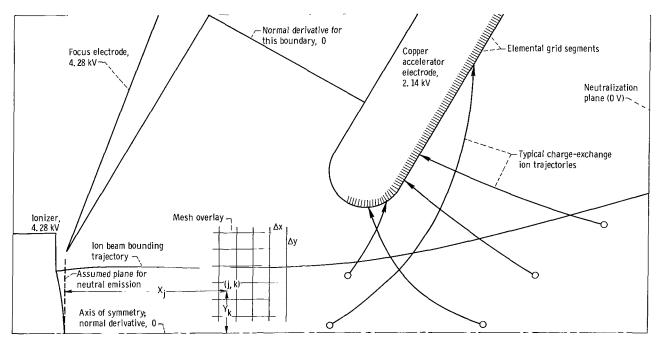


Figure 25. - Configuration used for charge-exchange erosion analysis. Charge-exchange ion trajectories started at centers of mesh squares.

The interaction cross-section equation is

$$\dot{N}_{j,k} = Q_{j,k} \mu_{j,k}^+ \rho_{j,k}^0 (\Delta V)$$
 (B1)

The numbers j and k identify a volume element in the beam region.

The interaction cross section Q for cesium ions and cesium atoms is given by Marino (ref. 14) as

$$Q_{j,k} = (26.8 - 1.46 \ln \varphi_{j,k})^2 \times 10^{-20}$$
 (B2)

The voltage  $\varphi_{j,k}$  is the difference between emitter potential and the potential at the center of the j, k charge-exchange volume and is determined from the digital computer solutions. The ion arrival rate  $\mu_{j,k}^+$  is also obtained from the digital computer solution.

Obtaining the neutral atom density  $\rho_{j,k}^0$  requires a neutral atom emission rate  $\nu^0$  from the emitter, which can be expressed as a fraction f of the ion emission rate  $\nu^+$ ; that is,

$$v^0 = fv^+$$

A value for f of  $10^{-2}$  is assumed. The quantities  $v^+$  and  $v^0$  are assumed constant across the emitter. The atom arrival rate is then calculated from the equation (ref. 15)

$$\frac{\mu_{j,k}^{0}}{\nu^{0}} = \frac{1}{2} \left[ \sqrt{4 \left(\frac{X_{j}}{w}\right)^{2} + \left(1 - \frac{2Y_{k}}{w}\right)^{2}} + \sqrt{4 \left(\frac{X_{j}}{w}\right)^{2} + \left(1 + \frac{2Y_{k}}{w}\right)^{2}} \right]$$
(B3)

Finally,

$$\rho_{j,k}^0 = \frac{\mu_{j,k}^0}{\overline{v}^0}$$

where

$$\overline{v}^0 = \sqrt{\frac{8kT_E}{\pi m}}$$

The arrival rate of impinging charge-exchange ions on the accelerator is determined by tracing out trajectories on the electrolytic tank analog. The Poisson potential distribution from the computer solution is established in the electrolytic tank. The exhaust beam is divided into a number of mesh squares (fig. 25, p. 20). Charge-exchange ion trajectories are then started with zero initial velocity from the centers of these mesh squares and traced on an xy-plotter. Figure 25 shows that the accelerator electrode has been divided into elemental segments on the downstream face. (No ions were found to impinge on the upstream face.) All ions formed in a particular mesh square are assumed to begin at the center of that square and to have the same energy when striking

the grid. Furthermore, it is assumed that they are equally distributed over the elemental grid segment and strike at the same angle of incidence. These assumptions are reasonable since the mesh squares and accelerator electrode segments are comparatively small. With these assumptions, the next step is to determine the sputtering damage for each elemental segment. Sputtering yields as a function of energy and angle of incidence for cesium ions (amu, 132.9) incident on copper were not available. Instead, data for xenon (amu, 131.3) on copper from reference 16 was used.

In summary, the charge-exchange ion formation rate from equation (B1) and the results of the electrolytic tank trajectory plots (fig. 25) yielded a solution for the distribution of ions striking the downstream face of the accelerator electrode. Then with the use of the sputtering data of reference 16 an erosion pattern was obtained. An example of an erosion pattern after 20 000 hours is shown in figure 7 (p. 6).

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